LiNX

the world's first fully integrated microprocessor controlled lower limb system.

The LiNX utilizes an integrated system of microprocessors, sensors and actuators for simultaneous control of the foot and knee.

Bi-directional communication coordinates the response to variations in terrain and speed, adjusting for the situational needs of the user.

Key Benefits include:

- Stop & support/Lock mode
- Controlled ramp descent with braking effect at the knee & ankle joint
- Assist mode during ramp ascent
- Dynamic stair descent
- Supportive resistance to flexion
- Integration of Mi2 technology and proximal power source reduces distal weight

Simplify your world





LiNX Amputee Profile Guide

A successful candidate for the LiNX should:

- have average voluntary control
- be able to control knee flexion during stancebe able to walk without aid
- be able to fully load the prosthesisbe a hydraulic functional ankle wearer
- be a K3 activity level, good community ambulator

Measurements	Patient ID/Approval Numbe	r (no names please)	Anticipated Fitting Date	
KC MM G G MM	Age Side L R Has t Able Able Insur Work Bilate Occupation/Activities/Expert	Sex <u>M</u> F Residual Limb Length in. true variable cadence to negotiate down rar to negotiate stairs, ste ance approval obtaine sers Compensation eral	Height <u>ft. in.</u> Present Prosthesis (specify keep over step	Precise Body Weight (without prosthesis) lbs. nee & foot)
Foot Sizecm Foot Shell Light Dark		Prosthetist		
 Address		City	State	Zip
Phone	Fax	Ema	ail Address	
Product Specifications Component Weight (size 26)				